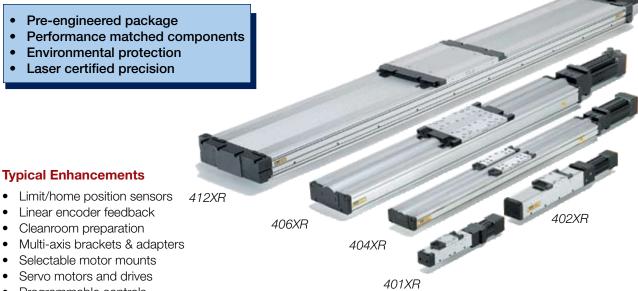
# **400XR Series Precision Linear Positioners**

Pre-engineered package

**Screw Driven** 

**Tables** 

- Performance matched components
- **Environmental protection** •





- .
- •
- Multi-axis brackets & adapters •
- Selectable motor mounts •
- Servo motors and drives
- Programmable controls .

401XR

402XR

Cable management system •

> 0 0 0 0 406XR 404XR



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[::::]

412XR

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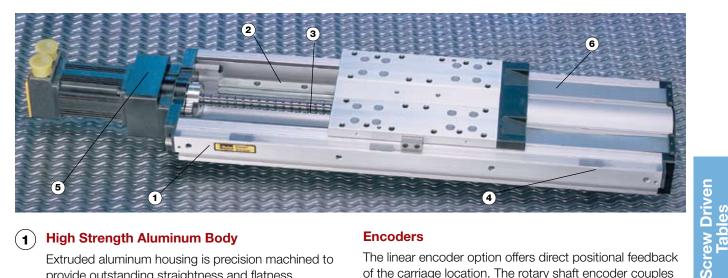
The "400XR" precision linear positioners family has achieved global recognition for consistent accuracy, reliable performance, high strength, and unmatched versatility. The XRs have excelled in industries such as life sciences, fiber optics and instrumentation, where the highest degree of precision is required. And yet, because of the rugged construction, strength, and sealed design, these units have been used extensively for industrial automation applications (packaging, automotive, etc).

The XR family offers an unrivaled array of features and options which are easily matched to fit any application, from the very basic to the highly complex. Premier performance, modular compatibility, and quick delivery have made these tables the perfect building blocks for precision multi-axis systems.

	401XR	402XR	404XR	406XR	412XR
Travel (mm)	300	600	600	2000	2000
Load (kg)	50	100	170	630	1470
Acceleration (m/sec <sup>2</sup> )	20	20	20	20	20







#### **High Strength Aluminum Body** (1)

Extruded aluminum housing is precision machined to provide outstanding straightness and flatness.

#### (2) Square Rail Linear Bearing

These tables are equipped with square rail carriage support bearings which provide high load carrying capabilities, smooth precise motion and dependable performance.

#### (3) High Efficiency Ballscrew Drive

Precision ground, or rolled ballscrew drive (5, 10, 20, 25, 32 mm lead) offers high throughput, efficiency, accuracy and repeatability.

#### Limit/Home Sensors (4)

Proximity sensors establish "end of travel" and "home" location and are easily adjustable over entire length to restrict the travel envelope.

#### (5) **Motor Mounts**

A large selection of servo and stepper motor sizes plus selectable mounting configurations (in-line, parallel) permit a wide variety of motor mounting possibilities.

#### (6) IP30 Rated Strip Seals

An anodized aluminum cover combined with stainless steel strip seals provide IP30 protection to interior components as well as enhance the overall appearance.

#### Encoders

The linear encoder option offers direct positional feedback of the carriage location. The rotary shaft encoder couples directly to the drive shaft to nullify any incurred mechanical error (particularly useful with the parallel motor mount). Not shown.

#### Shaft Brake

The electromagnetic shaft brake option couples directly to the drive screw and is employed primarily on vertical axes to halt carriage motion during a power loss. Not shown.

#### **Convenient Mounting Slots**

Continuous T-slots along the side of the table body provide a convenient means of mounting the table to a work

surface as well as mounting accessories to the table.

#### **Positive Pressure Port**

A standard port (1/8 NPT) for pressurizing the interior to prevent particle intrusion. (Standard on 404XR, 406XR, 412XR units.)

#### Easy Lube System

A standard option on some models, enables easy access for ballscrew and bearing lubrication.





#### **Cleanroom Preparation**

Class 10 cleanroom preparation is a standard option for the 400XR series. For detailed technical information on cleanroom preparation, contact Parker's Application Engineering Department at 1.800.245.6903

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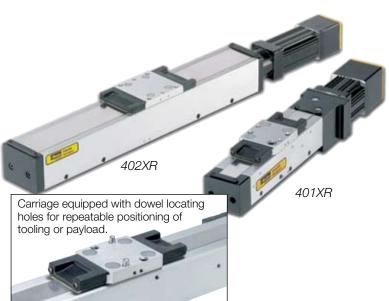
Screw Driven Tables

# 401XR (41 mm wide profile)

## 402XR Series (58 mm wide profile)

The 401XR and 402XR Series positioners enhance the 400XR family of precision linear positioners, addressing applications which involve precise positioning of smaller payloads within a very small space envelope.

These ballscrew driven positioners were developed to address the needs of industries such as photonics, life sciences, semiconductor, and instrumentation, where technology advancements dictate miniaturization of work envelopes.



### **Common Specifications**

		Prec	ision*	Stan	ndard
		401XR	402XR	401XR	402XR
Bidirectional Repeatability 2 mm lead 5 or 10 mm lead	μm	±1.3 ±1.3	_ ±1.3	±5 ±12	_ ±12
Duty Cycle	%	100	100	100	100
Maximum Acceleration	m/sec <sup>2</sup> (in/sec <sup>2</sup> )	20 (773)	20 (773)	20 (773)	20 (773)
Normal Load Capacity <sup>(1)</sup>	kgf (lbs)	50 (110)	100 (220)	50 (110)	100 (220)
Axial Load Capacity <sup>(1)</sup> 2 mm lead 5 or 10 mm lead	kgf (lbs)	5.5 (12.1) 15.5 (34.2)	_ 38 (84)	5.5 (12.1) 15.5 (34.2)	_ 38 (84)
Drive Screw Efficiency	%	80	80	80	80
Maximum Breakaway Torque	Nm (in-oz)	0.03 (4.2)	0.086 (12.0)	0.03 (4.2)	0.086 (12.0)
Maximum Running Torque <sup>(2)</sup>	Nm (in-oz)	0.028 (4.0)	0.08 (11.3)	0.028 (4.0)	0.08 (11.3)
Linear Bearing Coefficient of Friction		0.01	0.01	0.01	0.01
Ballscrew Diameter 2 mm lead 5 or 10 mm lead	mm	6 8	- 12	6 8	_ 12
Carriage Weight	kg (lbs)	0.045 (0.1)	0.11 (0.25)	0.045 (0.1)	0.11 (0.25)
* Requires linear aneodor option E3 or E4 (1)	Refer to life load charts for	ind lator in this post	ion (2) Potingo oct	philopod at 2 rpa	

\* Requires linear encoder option E3 or E4. (1) Refer to life load charts found later in this section. (2) Ratings established at 2 rps.

### **Travel/Screw Lead Dependent Specifications**

Travel (mm)		itional Ac	curacy* ( 402	μm) 2XR	•	htness tness	s Input Inertia 401XR		a (10 <sup>-₅</sup> kg-m²) 402XR		Screw Speed (revs/sec)		Unit Weight (kg)	
	Precision	Standard	Precision	Standard	401XR	402XR	2 mm	10 mm	5 mm	10 mm	401XR	402XR	401XR	402XR
50	10	20	-	-	20	-	0.6	-	-	-	100	-	1.0	-
100	10	20	10	20	20	20	0.9	-	12.0	-	100	90	1.2	2.3
150	12	20	12	20	20	20	1.1	-	15.0	-	100	90	1.3	2.6
200	16	30	16	30	25	25	_	4.7	20.0	_	100	90	1.5	2.8
300	18	40	18	40	25	25	-	5.2	-	25.0	100	90	1.7	3.2
400	_	-	21	40	_	30	-	_	-	29.0	_	95	_	3.8
600	-	-	25	50	-	30	-	-	-	39.0	-	50	-	4.8

\*Accuracy stated is at 20°C utilizing slope correction factor provided.





## 404XR Series (95 mm wide profile)

The 404XR is a sleek compact positioner (47.3 x 95 mm profile) capable of carrying 170 kg loads up to a distance of 700 mm. Its quick and accurate positioning capability can be attributed to a high strength extruded housing, square rail ball bearing system, and precision ground ballscrew drive.

With its low profile design the 404XR is ideal for height restricted applications, and its lightweight construction makes it well suited as secondary axes on multi-axis systems. These units offer a wide array of easily adapted options and accessories which permit easy configuration to specific requirements.



### **Common Specifications**

		Precision	Standard
Bidirectional Repeatability <sup>(5)</sup> Ballscrew Leadscrew	μm	±1.3 —	±3 ±12
Duty Cycle Ballscrew Leadscrew	%	100	100 75
Maximum Acceleration	m/sec² (in/sec²)	20 (773)	20 (773)
Normal Load Capacity <sup>(1)</sup>	kgf (lbs)	170 (375)	170 (375)
Axial Load Capacity <sup>(2)</sup> Ballscrew Leadscrew	kgf (lbs)	90 (198) -	90 (198) 25 (55)
Drive Screw Efficiency Ballscrew Leadscrew	%	90 30	90 30
Maximum Breakaway Torque	Nm (in-oz)	0.13 (18)	0.18 (26)
Maximum Running Torque <sup>(3)</sup>	Nm (in-oz)	0.11 (16)	0.17 (24)
Linear Bearing Coefficient of Friction		0.01	0.01
Screw Diameter Ballscrew Leadscrew	mm	16 —	16 12.7
Carriage Weight	kg (lbs)	0.70 (1.55)	0.70 (1.55)



- (1) Refer to life load charts found later in this section.
- (2) Axial load for parallel mount is limited by a maximum input torque of 2.5 Nm.
- (3) Ratings established at 2 rps.
- (4) Accuracy stated at 20°C utiliziting a factory provided slope correction factor; applies to in-line motor configurations only. Contact factory for parallel motor specifications.
- (5) Consult factory for specifications with linear encoder.
- (6) Consult factory for higher screw speeds.

#### **Travel/Screw Lead Dependent Specifications**

	Positional Accuracy <sup>(4) (5)</sup> (µm)			Straightness & Flatness		Input In	ertia (10 <sup>.</sup>	⁵ kg-m²)	Max Screw Speed <sup>(6)</sup>		Unit
Travel (mm)	Balls	crew	Leadscrew			5 mm	10 mm	20 mm	(revs	s/sec)	Weight
()	Precision	Standard		Ballscrew Leadscrew	5 mm	10 mm	20 mm	Ballscrew	Leadscrew	(kg)	
50	8	12	20	6	8	1.68	1.81	2.34	60	25	2.8
100	8	12	20	6	8	1.93	2.07	2.60	60	25	3.0
150	10	14	30	9	12	2.19	2.32	2.85	60	25	3.3
200	12	20	40	10	16	2.44	2.57	3.11	60	25	3.6
250	12	22	50	12	16	2.69	2.83	3.36	60	25	3.9
300	14	24	60	13	18	2.95	3.08	3.61	60	25	4.2
350	14	26	70	15	23	3.20	3.33	3.87	60	25	4.5
400	16	26	80	16	27	3.46	3.59	4.12	60	25	4.8
450	19	28	90	18	30	3.71	3.84	4.37	60	25	5.1
500	21	34	100	19	30	3.96	4.10	4.63	60	20	5.4
550	23	36	110	21	30	4.22	4.35	4.88	60	20	5.7
600	25	40	112	22	30	4.47	4.60	5.14	54	20	6.0

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## Screw Driven Tables

## 406XR Series (150 mm wide profile)

The 406XR can position high loads (up to 630 kgf) over distances up to two meters. Because of its size and strength (270 Nm, 200 lb-ft moment load capacity) this durable table is ideal as the base unit in a multi-axis system. From high resolution to high throughput, selectable ballscrew leads (5, 10, 20, 25 mm) make the desired resolution/velocity ratio easy to achieve, and stainless steel seal strips alleviate environmental concerns. Parallel Motor Mount (with limit/home sensor pack option)

### **Common Specifications**

		Precision	Standard
Bidirectional Repeatability (5)	μm	±1.3	±3
Duty Cycle	%	100	100
Maximum Acceleration	m/sec² (in/sec²)	20 (773)	20 (773)
Normal Load Capacity <sup>(1)</sup>	kgf (lbs)	630 (1390)	630 (1390)
Axial Load Capacity <sup>(2)</sup> 0 to 600 mm Travel 700 to 2000 mm Travel	kgf (lbs)	90 (198) -	90 (198) 200 (440)
Drive Screw Efficiency	%	90	90
Maximum Breakaway Torque 0 to 600 mm Travel 700 to 2000 mm Travel	Nm (in-oz)	0.13 (18) –	0.18 (26) 0.39 (55)
Maximum Running Torque <sup>(3)</sup> 0 to 600 mm Travel 700 to 2000 mm Travel	Nm (in-oz)	0.11 (16)	0.17 (24) 0.34 (48)
Linear Bearing Coefficient of Friction		0.01	0.01
Ballscrew Diameter 0 to 600 mm Travel 700 to 2000 mm Travel	mm	16 -	16 25
Carriage Weight	kg (lbs)	2.7 (5.94)	2.7 (5.94)



- (1) Refer to life load charts found later in this section.
- (2) Axial load for parallel mount is limited to: 140 lbs for the 5, 10 and 20 mm lead drives: 104 kg (230 lbs) for 25 mm lead drives
- (3) Ratings established at 2 rps.
- (4) Accuracy stated at 20°C utiliziting a factory provided slope correction factor; applies to in-line motor configurations only. Contact factory for parallel motor specifications.
- (5) Consult factory for specifications with linear encoder.
- (6) Consult factory for higher screw speeds.

### **Travel/Screw Lead Dependent Specifications**

Travel (mm)		Positional Accuracy <sup>(4) (5)</sup> (μm)		In	put Inertia	a (10⁻⁵ kg-r	Max Screw Speed <sup>(6)</sup>	Unit Weight		
(1111)	Precision	Standard	& Flatness	5 mm	10 mm	20 mm	25 mm	(revs/sec)	(kg)	
100	8	12	6	3.34	3.85	5.90	-	60	8.7	
200	12	20	10	3.92	4.43	6.48	-	60	10.0	
300	14	24	13	4.50	5.01	7.06	-	60	11.3	
400	16	26	16	5.08	5.59	7.64	-	60	12.6	
500	21	34	19	5.65	6.17	8.22	-	55	13.9	
600	25	40	22	6.23	6.75	8.80	-	44	15.2	
700	-	92	25	36.51	37.02	-	40.61	47	19.2	
800	-	94	29	39.96	40.47	-	44.07	47	20.7	
900	-	103	32	43.41	43.93	-	47.52	47	22.2	
1000	-	105	35	46.87	47.38	-	50.97	47	23.7	
1250	_	118	42	55.50	56.01	-	59.61	35	27.6	
1500	-	134	50	64.14	64.65	-	68.24	26	31.4	
1750	_	154	57	72.77	73.28	-	76.88	20	35.2	
2000	-	159	65	81.40	81.92	-	85.51	16	39.1	





The 412XR is a rugged heavy duty linear table (285 mm x 105 mm profile) that enables massive loads (up to 1470 kgf) to be precisely positioned over distances up to two meters. Single point "easy lube" port is standard on carriage assembly for simple servicing and a convenient adapter plate (#100-6784-01) is available for easy X-Y configuration.

An unrivaled array of options combined with mounting compatibility with the smaller 400XR tables makes the 412XR ideal as the base unit for multiaxis positioning of heavier payloads.

#### **Common Specifications**

		Stan	dard
Screw Lead	mm	5, 10, 25	32
Bidirectional Repeatability <sup>(4)</sup>	μm	±5	±5
Duty Cycle	%	100	100
Maximum Acceleration	m/sec² (in/sec²)	20 (773)	20 (773)
Normal Load Capacity <sup>(1)</sup>	kg (lbs)	1470 (3241)	1470 (3241)
Axial Load Capacity	kg (lbs)	200 (441)	460 (1014)
Drive Screw Efficiency	%	90	80
Maximum Breakaway Torque	Nm (in-oz)	0.61 (86)	0.76 (108)
Maximum Running Torque <sup>(2)</sup>	Nm (in-oz)	0.55 (78)	0.69 (98)
Linear Bearing Coefficient of Friction		0.01	0.01
Ballscrew Diameter	mm	25	32
Carriage Weight	kg (lbs)	12 (27)	13 (28)

(1) Refer to life load charts found later in this section.

(2) Ratings established at 2 rps.

(3) Accuracy stated at 20°C utiliziting a factory provided slope correction factor; applies to in-line motor configurations only. Contact factory for parallel motor specifications

(4) Consult factory for specifications with linear encoder.

(5) Consult factory for higher screw speeds.

#### **Travel/Screw Lead Dependent Specifications**

Travel Positional		Straightness	Input Inertia (10 <sup>-5</sup> kg-m <sup>2</sup> )				Max Screw Speed <sup>(5)</sup> (revs/sec)		Unit Weight (kg)	
(mm)	μm)	& Flatness	5 mm	10 mm	25 mm	32 mm	5, 10, 25 mm	32 mm	5, 10, 25 mm	32 mm
150	64	9	27.20	29.45	46.76	98.20	47	42	39.6	41.5
250	66	12	30.21	32.46	49.78	106.28	47	42	42.9	45.0
350	71	15	33.23	35.48	52.79	114.37	47	42	46.2	48.5
650	91	24	42.27	44.52	61.83	138.63	47	42	56.1	59.0
800	94	29	46.79	49.04	66.35	150.76	47	42	61.0	64.2
1000	105	35	52.81	55.06	72.37	166.94	45	42	67.6	71.2
1250	118	42	58.84	61.09	78.40	183.11	34	41	74.2	78.2
1500	134	50	67.87	70.12	87.44	207.38	24	31	84.1	88.7
1750	154	57	75.41	77.66	94.97	227.59	18	24	92.4	97.5
2000	159	65	82.94	85.19	102.50	247.81	15	19	100.6	106.2

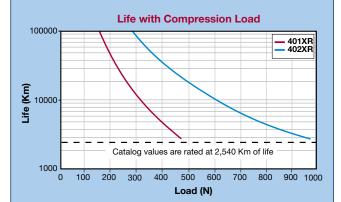


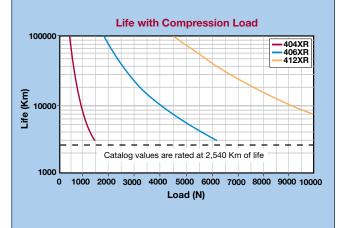
## 400XR Series Life/Load

The following performance information is provided as a supplement to the product specifications pages. The following graphs are used to establish the table life relative to the applied loads. The useful life of a linear table at full catalog specifications is dependent on the forces acting upon it. These forces include both static components resulting from payload weight, and dynamic components due to acceleration/ deceleration of the load. In multi-axes applications, the primary positioner at the bottom of the stack usually establishes the

#### Normal Load (Compression)

These graphs provide a "rough cut" evaluation of the support bearing life/load characteristics. The curves show the life/load relationship when the applied load is centered on the carriage, normal (perpendicular) to the carriage mounting surface.



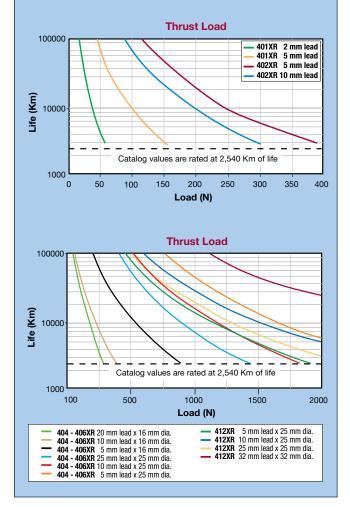


load limits for the combined axes. When determining life/load, it is critical to include the weight of all positioning elements that contribute to the load supported by the primary axis. *Catalog load specifications are rated for 100 million inches of travel or 2,540 km.* 

For final evaluation of life vs load, including off center, tension, and side loads refer to the charts and formulas found on our web site at www.parkermotion.com.

### **Axial Load (Thrust)**

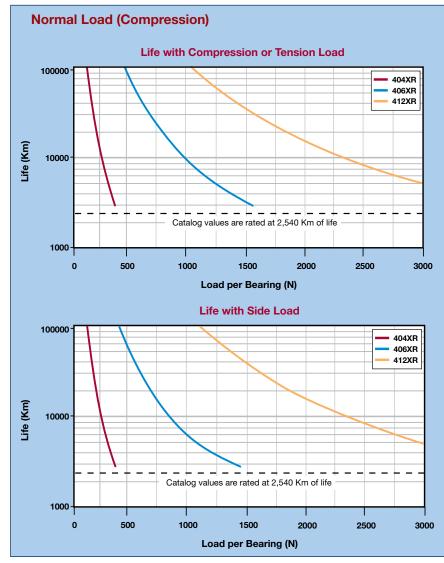
These graphs illustrate table ballscrew life relative to the axial load.







## 400XR Series Bearing Life/Load\*



\*For 401XR and 402XR moment loading capacities, please refer to the maintenance manual.

These charts are to be used in conjunction with the corresponding formulas found in the product manuals at www.parkermotion.com to establish the life/load for each bearing (4 per table).

Several dimensions, which are specific to each linear positioning table model, and the load geometry are required for these computations. These dimensions are supplied in the catalog information for each positioner. The dimensions are referenced as follows:

- d1 bearing block center-to-center longitudinal spacing
- d2 bearing rail center-to-center lateral spacing
- **da** Rail center-to-carriage mounting surface

	d1	d2	da
404XR	80	57	28
406XR	114	90.3	42.5
412XR	205	192	43

Refer to Parker's website www.parkermotion.com for moment loading and other engineering data.



## Screw Driven Tables

## Home or Limit Sensor Options

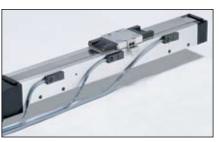
End of Travel and Home Sensors for the 400XR series are available in a variety of styles. The sensors can be ordered as part of the table or as separate components



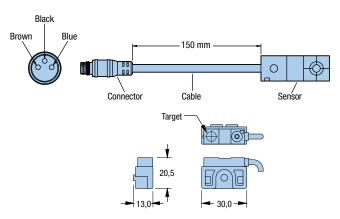
with the associated mounting hardware or in an enclosed sensor pack. A 5 meter high-flex extension cable (Part No. 003-2918-01) is included for use with the 401XR thru 406XR models having the locking connector option.

- NPN (Sinking) or PNP (Sourcing)
- Normally Closed (N.C.) or Normally Open (N.O.)
- Flying Leads or Locking Connector

Specification	Specifications						
Input Power	5-30 VDC, 20 mA						
Output	100mA max						
Wire Color	(+) Supply: Brown						
Code	(–) Supply: Blue NO Output: Black NC Output: White						



401XR Limits and Home Sensor



Sensor / Bracket Detail

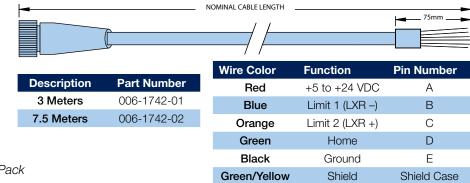
Order Code	Part Number*	Switch Type	Logic	Cable Length	<b>Connector Option</b>
H2 or L2	006-1639-01	N.C.	Sinking	3.0 m	Flying Leads
H3 or L3	006-1639-02	N.O.	Sinking	3.0 m	Flying Leads
H4 or L4	006-1639-03	N.C.	Sourcing	3.0 m	Flying Leads
H5 or L5	006-1639-04	N.O.	Sourcing	3.0 m	Flying Leads
H6 or L6	006-1639-09	N.C.	Sinking	150 mm	Locking Connector
H7 or L7	006-1639-08	N.O.	Sinking	150 mm	Locking Connector
H8 or L8	006-1639-11	N.C.	Sourcing	150 mm	Locking Connector
H9 or L9	006-1639-10	N.O.	Sourcing	150 mm	Locking Connector
H11 or L11	See chart below	N.C.	Sinking	See chart below	Sensor Pack
H12 or L12	See chart below	N.O.	Sinking	See chart below	Sensor Pack
H13 or L13	See chart below	N.C.	Sourcing	See chart below	Sensor Pack
H14 or L14	See chart below	N.O.	Sourcing	See chart below	Sensor Pack

\* Applies to 401XR thru 406XR models. 412XR models have limits and homes internally mounted with a connector termination. Sensor triggers (targets) ordered separately.

sor P	ack	Cable	



406XR with Limit and Home Sensor Pack





## Linear Encoder Options (Tape Scale)

A linear position feedback device which mounts directly to the table carriage. (Factory installation required.)



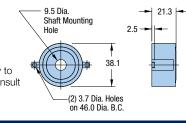
- 1.0 µm resolution0.5 µm resolution
- 0.1 µm resolution

## **Rotary Encoder Option**

Modular rotary encoder couples directly to the drive screw for position feedback and is easily field installed. The rotary encoder cannot be installed with the brake assembly option.

5000 counts/rev

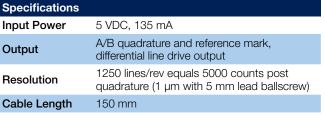
Note: Dimensions shown apply to 404XR and 406XR models. Consult factory for 412XR dimensions.



Specifications	
Input Power	5 VDC, 150mA
Output	A/B quadrature and reference mark, differential line drive output
Resolution	1.0, 0.5, 0.1 micron
Cable Length	3 m

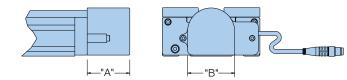


401XR with Linear Encoder plus Sensor Pack



## **Brake Assembly Option**

Electromagnetic brake assembly used to prevent "backdriving" in vertical applications. The brake option includes a 5 m extension cable. The brake option is easily field installed. The brake option cannot be installed with the rotary encoder option.





404XR with Brake Option

			Holding	Dimensions (mm)	
Table Series	Part Number	Input Power	Torque	Α	В
401XR/402XR	—	—	—	—	_
404XR	006-1627-01	24 VDC, 0.46 A	2.0 Nm	41.5	46.0
406XR	006-1656-01	24 VDC, 0.5 A	4.5 Nm	49.9	57.5
412XR	002-1916-01	24 VDC, 0.75 A	9.0 Nm	54.0	72.0



## **Dowel Pinning Options\***

Standard dowel pin locating holes are offered on most 400XR units to facilitate repeatable mounting of tooling or payload.\*

In addition, pinning options are offered for precise orthogonal mounting of the second axis in a multi-axis system. In this case, the bottom side of the table base is match drilled and reamed to the first axis to provide exact orthogonal location. This convenient option eliminates concerns regarding contamination or damage often associated with machining for locating pins in an assembled unit.

\*Not available with 401XR or 402XR or 50 mm travel 404XR.



Two locating dowel pins shown in carriage





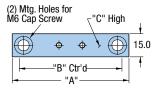
## 400XR Series Accessories

## **Riser Plate Accessory**

Used to raise the table base to provide clearance for motors.

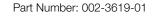
Model	Part Number
401XR	002-2063-01
402XR	002-2064-01
404XR	002-3619-01
406XR	002-3625-01
412XR	-

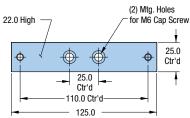
**401XR/402XR** Part Number: 002-2063-01/ 002-2064-01



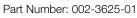
	Dimensions (mm)				
Table Series	Α	В	С		
401XR	65.0	50.4	17.0		
402XR	90.0	75.4	10.0		

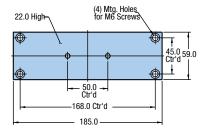
#### 404XR





## 406XR





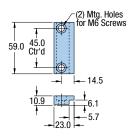
#### **Toe Clamp Accessory**

Used for convenient outboard mounting of table to a base plate, riser plates, Z-axis bracket, or other 400XR table. All hardware is included.

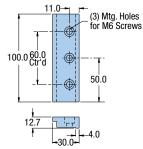
Model	Part Number
404XR	002-3618-01
406XR	002-3624-01
412XR	002-2160-01



**406XR** Part Number: 002-3624-01



412XR Part Number: 002-2160-01









**Tables** 



	Second Axis (Y or Z)*									
Base Axis (X) *	Orientation	401 50 mm	XR >50 mm	402XR	404XR	404LXR	406XR	406LXR	412XR 412LXR	Wedge
(^)				402AN	404AN	404LAN	400AN	400LAN	412LAN	wedge
	X-Y	002-2126-01	002-2065-01	_	_	_	_	_	_	_
401XR	X-Y Cartesian	002-2123-01	002-2068-01	-	-	_	_	-	_	-
	X-Z	_	101-0955-01	_	_	_	_	_	_	_
	X-Z Side Mount		101-0955-01		_	_	_	_	_	—
	X-Y	002-2130-01	002-2066-01	002-2066-01	_	_	_	_	_	_
402XR	X-Y Cartesian		002-2069-01	002-2069-01	-	-	-	—	—	-
	X-Z	—	002-2069-01	002-2069-01	_	_	_	_	_	_
	X-Z Side Mount		002-2069-01	002-2069-01	-	-	_	_	—	-
	X-Y	100-9193-01	100-9193-01	100-9193-01	Direct Mount*	100-9584-01	_	_	_	100-9274-01
	X-Y Carriage to Carriage	-	-	-	100-3945-01	100-3945-01	-	-	-	-
404XR 404LXR	X-Y Cartesian Right Hand	002-2162-02	002-2162-02	002-2162-02	_	_	_	—	—	_
404LXK	X-Y Cartesian Left Hand	002-2162-02	002-2162-02	002-2162-02	—	—	-	—	—	-
	X-Z	_	_	_	002-1839-01	_	_	_	_	_
	X-Z Side Mount	_	_	_	002-1840-01	_	_	_	_	_
	X-Y	100-9194-01	100-9194-01	100-9194-01	Direct Mount*	Direct Mount*	Direct Mount*	Direct Mount*	_	100-9274-01
406XR	X-Y Carriage to Carriage	-	-	-	100-4191-01	100-4191-01	100-4191-01	100-4191-01	-	-
406LXR	X-Y Cartesian	_	_	_	002-2163-01	002-2163-01	_	_	_	_
	X-Z	_	_	_	002-1823-01	_	002-1817-01	_	_	_
	X-Z Side Mount	_	_	_	002-1824-01	_	002-1818-01	_	_	_
412XR	X-Y	-	-	-			Direct Mount* or Toe Clamp		100-6784-01	_
412LXR	X-Y Cartesian	_	_	_	_	_	002-2164-01	002-2164-01	_	_
ZP 200 Wedge	X-Y	-	-	-	100-9274-01	100-9274-01 or Toe Clamp		100-9274-01	-	_

\* An adaptor plate (100-3945-01) is required whenever the X-axis is a parallel motor mount model. If the Y-axis is 404XR with 50 mm stroke, a special plate or toe clamp option is required.

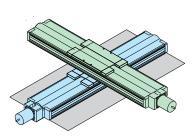


**400XR Series Configurations** 



## 400XR Multi Axis Configurations

These diagrams show the most popular variations of multiaxis configurations. Both standard and custom brackets are available. Standard X-Y orientation will place the X axis motor at the 6 o'clock position and the Y axis motor at the 3 o'clock position.



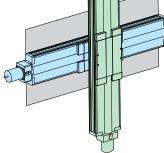
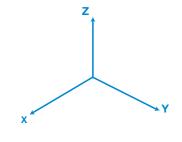
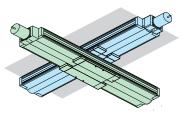


Figure 1 Two Axis (X-Y) Horizontal Mounting

Figure 2 Two Axis (X-Z) Vertical Mounting





**Tables** 

Figure 3 Two Axis (X-Y) Inverted Mounting

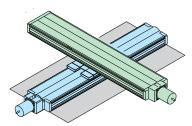


Figure 4 Two Axis-Carriage to Carriage (Y Axis Inverted)

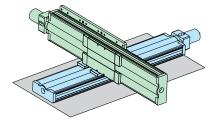


Figure 5 Two Axis (X-Y) Cartesian Horizontal Mounting

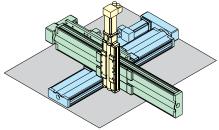


Figure 6 Three Axis (X-Y-Z) Cartesian Horizontal Mounting

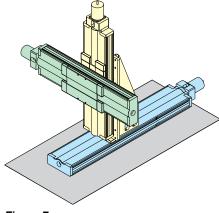


Figure 7 Three Axis (X-Z-Y) Horizontal Mounting

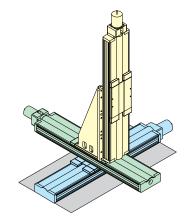
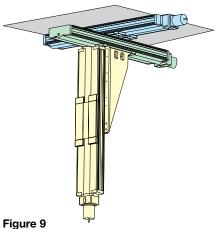


Figure 8 Three Axis (X-Y-Z) Horizontal Mounting



Three Axis (X-Y-Z) Inverted Mounting

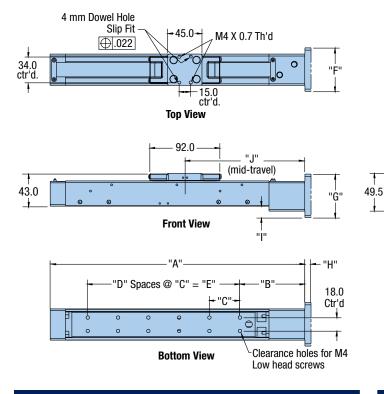
Screw Driven

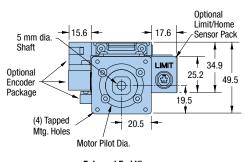




#### **Dimensions (mm)**

## **401XR Dimensions**





Enlarged End View (with Encoder and Limit/Home Sensor Pack Option)

-40.9-

 $(\bigcirc)$ 

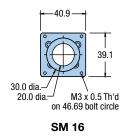
**End View** 

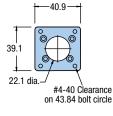
	Travel	Dimensions (mm)					
Model	(mm)	Α	В	С	D	E	J
401050XR	50	209.3	82.8	80.0	1	80.0	123.0
401100XR	100	284.3	80.3	40.0	4	160.0	160.0
401150XR	150	334.3	85.3	40.0	5	200.0	185.0
401200XR	200	384.3	90.3	40.0	6	240.0	210.0
401300XR	300	509.3	92.8	40.0	9	360.0	260.0

	Order	Dimensions (mm)					
Motor Size	Code	F	G	Н	1		
SM 16	M2	40.9	39.1	-	6.5		
NEMA 23/SM 23	M3	57.2	57.2	4.0	15.6		
NEMA 17	M37	40.9	39.1	-	6.5		
BE 23	M61	57.2	57.2	8.0	15.6		

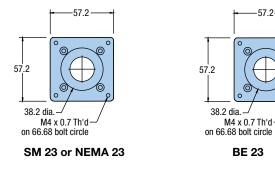
## **In-Line Motor Adapters**

Used to easily accommodate the mounting of different servo or stepper motors.





NEMA 17

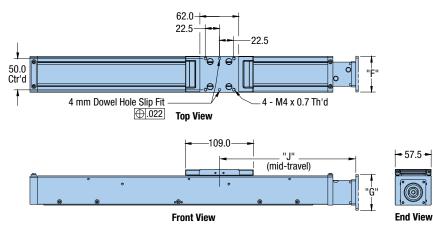


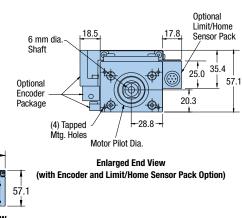


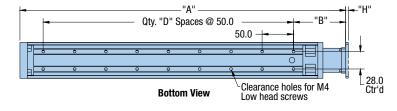


**Dimensions (mm)** 

### **402XR Dimensions**





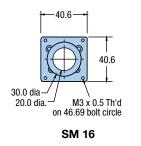


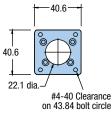
	Travel				
Model	(mm)	Α	В	D	J
402100XR	100	320.5	83.5	4	184.0
402150XR	150	370.5	83.5	5	214.0
402200XR	200	420.5	83.5	6	234.0
402300XR	300	520.5	83.5	8	284.0
402400XR	400	620.5	83.5	10	334.0
402600XR	600	820.5	83.5	14	434.0

Order	Dimensions (mm)				
Code	F	G	Н		
M2	40.6	40.6	-		
M3	57.2	57.2	4.0		
M37	40.6	40.6	_		
M61	57.2	57.2	8.0		
	M2 M3 M37	Order         F           M2         40.6           M3         57.2           M37         40.6	Order         F         G           M2         40.6         40.6           M3         57.2         57.2           M37         40.6         40.6		

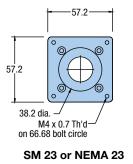
## **In-Line Motor Adapters**

Used to easily accommodate the mounting of different servo or stepper motors.

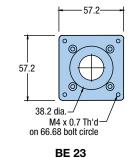




**NEMA 17** 



 $\bigcirc$ 



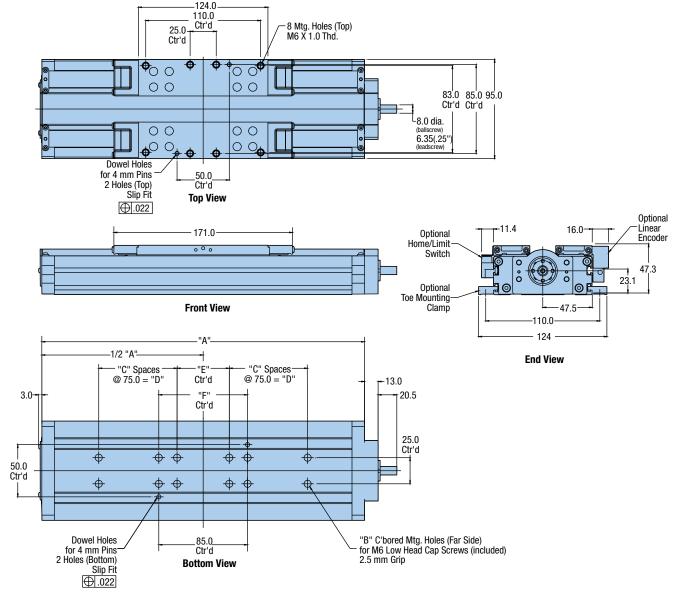


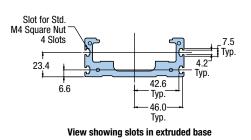
Screw Driven Tables



## **404XR Dimensions**

Dimensions (mm)





	Travel	Dimensions (mm)					
Model	(mm)	Α	В	С	D	Е	F
404050XR	50	259	4	-	-	-	-
404100XR	100	309	12	1	75.0	50.0	85.0
404150XR	150	359	12	1	75.0	50.0	85.0
404200XR	200	409	12	1	75.0	50.0	85.0
404250XR	250	459	16	2	150.0	50.0	85.0
404300XR	300	509	16	2	150.0	50.0	85.0
404350XR	350	559	16	2	150.0	50.0	85.0
404400XR	400	609	20	3	225.0	50.0	85.0
404450XR	450	659	20	3	225.0	50.0	85.0
404500XR	500	709	20	3	225.0	50.0	85.0
404550XR	550	759	24	4	300.0	50.0	85.0
404600XR	600	809	24	4	300.0	50.0	85.0

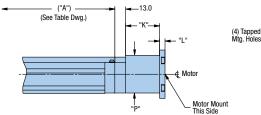


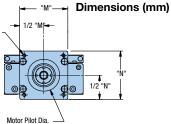
## 404XR Dimensions



In-line motor mounting allows the motor to be mounted directly to the drive screw via the selected motor coupling.

Used to easily accommodate the mounting of different frame sizes. These adapter plates can be ordered separately by part number below.

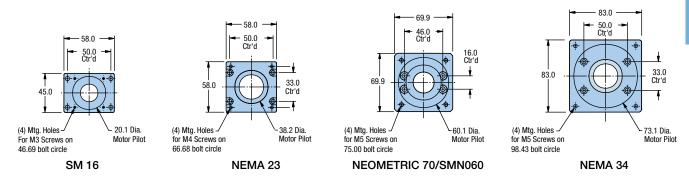




/ Driven bles

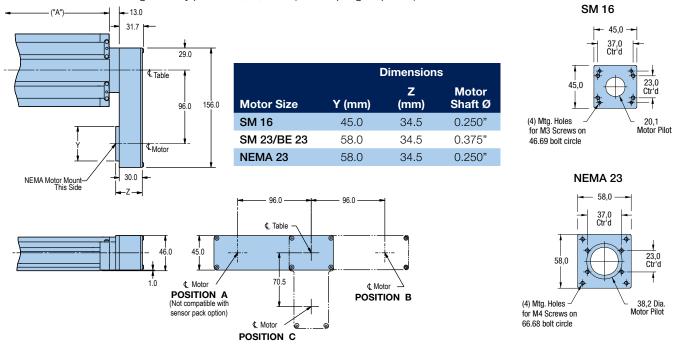
Screw

	<u>.</u>			Dim	ensions (	mm)	
Motor Size	Order Code	Max. Motor Shaft Ø	к	L	М	Ν	Ρ
SM 16	M2	9.5	41.0	4.3	53.0	45.0	45.0
NEMA 23	MЗ	9.5	41.0	6.5	83.0	58.0	45.0
NEMA 34	M4	9.5	41.0	12.5	83.0	83.0	45.0
NEO 70	M21	11.0	53.0	-	69.9	69.9	69.9



## 404XR Parallel Motor Mounting

Parallel motor mounting is employed whenever a shorter overall unit length is needed. The motor is positioned along the sides or bottom of the table as designated by position A, B, or C. (No coupling required.)



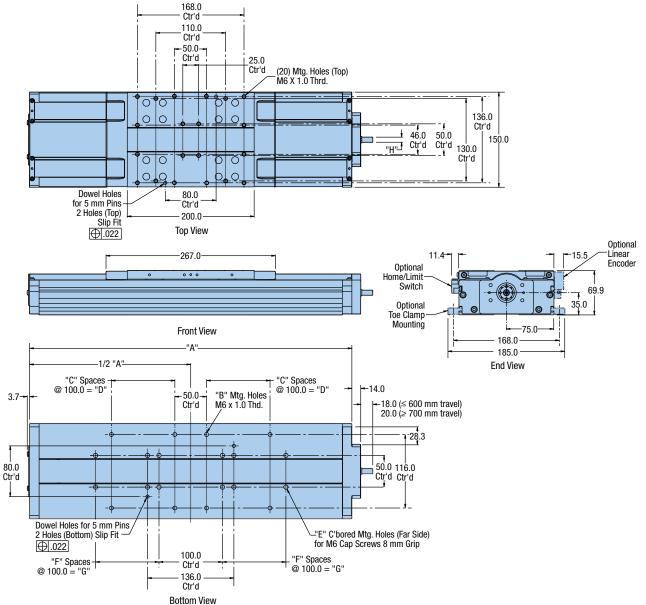


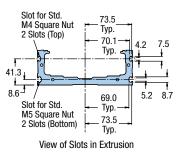
Parker Hannifin Corporation Electromechanical Automation Division Irwin, Pennsylvania



**Dimensions (mm)** 

## **406XR Dimensions**





	Travel	Ballscrew	Dimensions (mm)												
Model	(mm)	Ø	Α	В	С	D	Е	F	G	Н					
4060100XR	100	16	408	8	1	100.0	12	1	100.0	8.0					
4060200XR	200	16	508	8	1	100.0	12	1	100.0	8.0					
4060300XR	300	16	608	12	2	200.0	16	2	200.0	8.0					
4060400XR	400	16	708	12	2	200.0	16	2	200.0	8.0					
4060500XR	500	16	808	16	З	300.0	20	3	300.0	8.0					
4060600XR	600	16	908	16	3	300.0	20	3	300.0	8.0					
4060700XR	700	25	1008	20	4	400.0	24	4	400.0	10.0					
4060800XR	800	25	1108	20	4	400.0	24	4	400.0	10.0					
4060900XR	900	25	1208	24	5	500.0	28	5	500.0	10.0					
4061000XR	1000	25	1308	24	5	500.0	28	5	500.0	10.0					
4061250XR	1250	25	1558	32	7	700.0	32	6	600.0	10.0					
4061500XR	1500	25	1808	36	8	800.0	40	8	800.0	10.0					
4061750XR	1750	25	2058	40	9	900.0	44	9	900.0	10.0					
4062000XR	2050	25	2308	44	10	1000.0	48	10	1000.0	10.0					

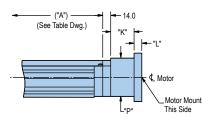


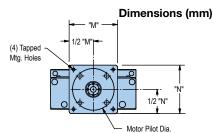
Screw Driven Tables

## 406XR In-Line Motor Mounting

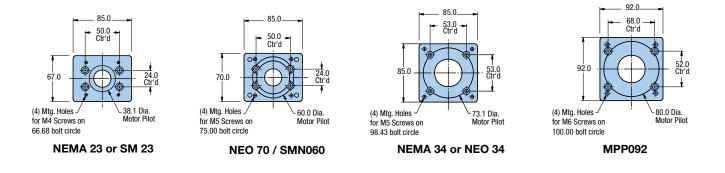
In-line motor mounting allows the motor to be mounted directly to the drive screw via the selected motor coupling.

Used to easily accommodate the mounting of different frame sizes. These adapter plates can be ordered separately by part number below.



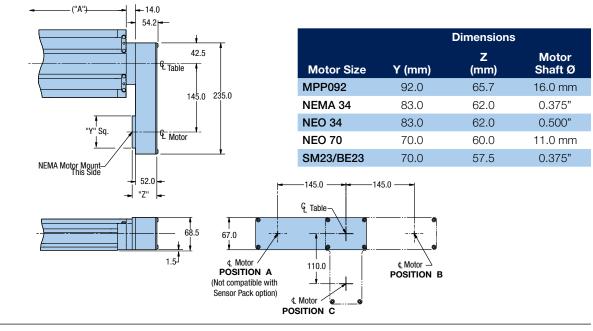


	Order	Max. Motor		Dim	(mm)		
Motor Size	Code	Shaft Ø	К	L	М	Ν	Р
MPP092	M90	16.0	53.0	12.5	92.0	92.0	69.0
NEMA 23/SM 23	MЗ	9.5	41.0	-	85.0	67.0	67.0
NEMA 34	M4	16.0	53.0	13.5	85.0	85.0	70.0
NEO 34	M17	16.0	53.0	13.5	85.0	85.0	70.0
NEO 70	M21	16.0	53.0	-	85.0	70.0	70.0
NEO 92	M29	16.0	53.0	12.5	92.0	92.0	70.0



## 406XR Parallel Motor Mounting

Parallel motor mounting is employed whenever a shorter overall unit length is needed. The motor is positioned along the sides or bottom of the table as designated by position A, B, or C. (No coupling required.)

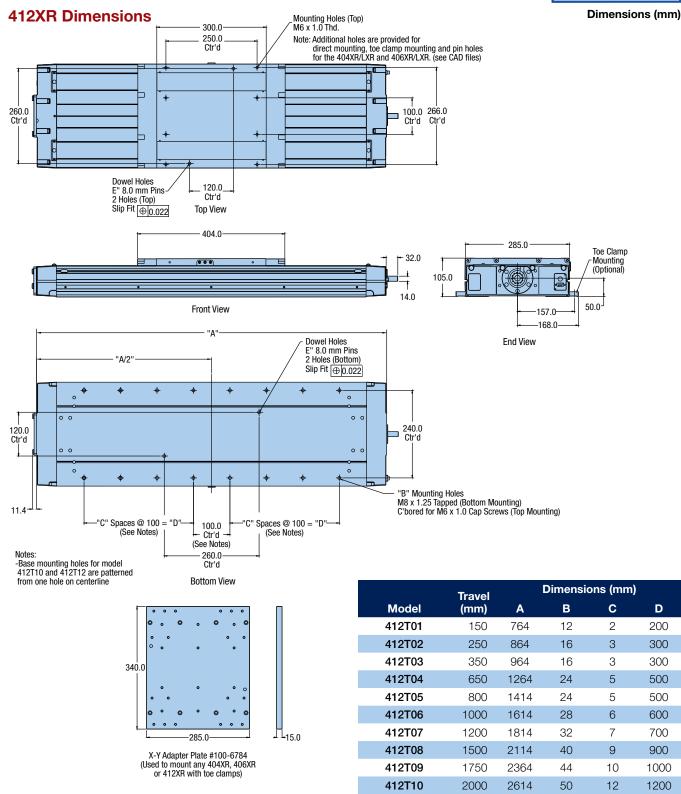




## **412XR Dimensions**

**Screw Driven Tables** 

2D & 3D CAD **Download from** parkermotion.com





D

200

300

300

500

500

600

700

900

1000

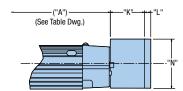
1200

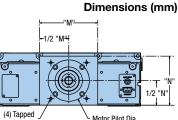


## 412XR In-Line Motor Mounting

In-line motor mounting allows the motor to be mounted directly to the drive screw via the selected motor coupling.

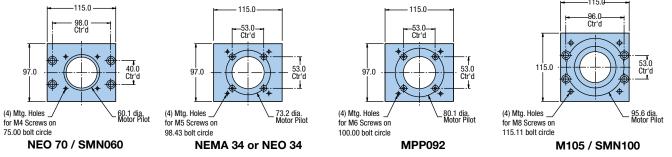
Used to easily accommodate the mounting of different frame sizes. These adapter plates can be ordered separately by part number below.





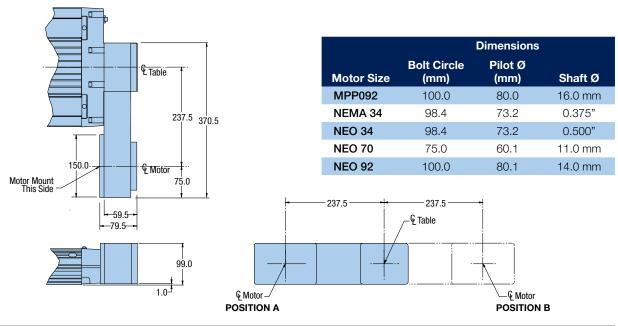
(4) Tapped / Motor Pilot Dia. Mtg. Holes

	Order		Dimensio	ons (mm)	
Motor Size	Code	К	L	М	Ν
MPP092	M90	68.0	12.0	115.0	97.0
M105, SMN100	M33	100.0	-	115.0	115.0
NEMA 34	M4	68.0	12.0	115.0	97.0
NEO 34	M17	68.0	12.0	115.0	97.0
NEO 70	M21	68.0	-	115.0	97.0
NEO 92	M29	68.0	12.0	115.0	97.0
				<u>н</u> 115 Ф	



### 412XR Parallel Motor Mounting

Parallel motor mounting is employed whenever a shorter overall unit length is needed. The motor is positioned along the sides or bottom of the table as designated by position A, B, or C. (No coupling required.)



Parker Hannifin Corporation Electromechanical Automation Division Irwin, Pennsylvania



			1	2	3	4	5	6	0	8	9	10	11	12
	Order	Example:	401	100	XR	Μ	S	D9	H3	L2	C3	M2	E2	R1
0	<b>Series</b> * 401	r				8	Lin L1		<b>1sor **</b> None					
	401						L2			urrent S	inkina F	-lying Le	eads	
2	<b>Travel –</b> 050	50					L3 L4		N.O. Cı	urrent S	Sinking F	Flying Le Flying I	eads	
	100 150	100 150				L5				-	g Flying I			
	200	200					L6				-	_ocking		
	300	300					L7				-	_ocking		
_							L8 L9				-	Lockin	-	
3	Model						L9 L11					g Lockin Sensor F	0	ector
	XR	Linear Table					L12				-	Sensor F		
4	Mountii	20					L13				-	Sensor		
G	M	Metric					L14				-	g Sensoi		
5	Grade					9	Мс	otor Co	oupling	I				
Ŭ	S	Standard					C1							
	Р	Precision (E3 or E4 enco	oder optior	n require	ed)		C2	٦						
							C3				,	Bellows		
6	Drive Se					C5 C2		9.5 mm 5 mm ((	`	'	e Bellov	VS		
	D3	10 mm Lead					C2		5 mm (0					
	D9	2 mm Lead					UL:	0		5.20 11)	DOIC D	010003		
0	Home S	Sensor **				10		otor M						
	H1	None					M2		SM 16			0		
	H2	N.C. Current Sinking Fly	-				M3 M3					0		
	H3	N.O. Current Sinking Fly	-				M6		NEMA BE 23 I			0		
	H4	N.C. Current Sourcing F					IVIO	, i			viouritii	19		
	H5	N.O. Current Sourcing F				(1)	En	coder	Optior	า				
	H6 H7	N.C. Current Sinking Lo N.O. Current Sinking Lo	•			Ŭ	E1		None					
	H8	N.C. Current Sourcing L	-				E2		1.0 µm	Resolu	tion			
	H9	N.O. Current Sourcing L	•				E3		0.5 µm					
	H11	N.C. Current Sinking Se					E4		0.1 µm	Resolu	tion			
	H12	N.O. Current Sinking Se				~	_							
	H13	N.C. Current Sourcing S	Sensor Pac	k		12	R1		Require	d Desig	gnator			
	H14	N.O. Current Sourcing S	Sensor Pac	k										

#### \* Drive Screw Lead Availability

Travel	401	IXR
Iravei	2 mm	10 мм
50	•	
100	•	
150	•	
200		•
300		•

 $^{\star\star}$  50 mm stroke 401XR may only allow room for 2 sensors in sensor pack.





			1	2	3	4	5	6	7	8	9	10	11	12
	Order	Example:	402	100	XR	М	S	D9	H3	L2	C3	M2	E2	R1
1	Series 402	-				8	L1	nit Ser	<b>isor</b> None					
3	<b>Travel -</b> 100 150 200 300 400 600	- mm * 100 150 200 300 400 600					L2 L3 L4 L5 L6 L7 L8 L9		N.C. Cu N.O. Cu N.C. Cu N.O. Cu N.C. Cu N.O. Cu	urrent S urrent S urrent S urrent S urrent S urrent S urrent S	inking F ourcing ourcing inking L inking L ourcing ourcing	Flying Le Flying I Ocking Ocking Ocking	eads _eads Leads Connea Connea g Conn g Conn	ctor ector
3	<mark>Model</mark> XR	Linear Table					L11 L12 L13	2 3	N.C. Cı N.O. Cı N.C. Cı	urrent S urrent S	Sinking Sourcing	Sensor F I Sensor	Pack <sup>-</sup> Pack	
4	<mark>Mount</mark> i M	<b>ng</b> Metric				9	L14 Mo		N.O. Cu Dupling		Sourcing	j Sensor	r Pack	
5	<mark>Grade</mark> S P	Standard Precision (E3 or E4 en	ed)		C1 C2 C3 C4		No Cou 6.3 mm 6.3 mm	6						
6	Drive S D2 D3	5 mm Lead 10 mm Lead					C4         9.5 mm (0.375 in) Bore           C5         9.5 mm (0.375 in) Bore           C24         5 mm (0.20 in) Bore Old           C25         5 mm (0.20 in) Bore Bel           *NEMA 23 frame size only (M3, M61)							
0	Home \$ H1 H2 H3 H4 H5 H6 H7 H8	None N.C. Current Sinking F N.O. Current Sinking F N.C. Current Sourcing N.O. Current Sourcing N.C. Current Sinking L N.O. Current Sinking L N.C. Current Sourcing	Tying Leads Flying Leads Flying Leads ocking Conr ocking Conr Locking Conr	s nector nector nnector		0	Mo M2 M3 M3 M6 End	otor M 7 1 coder	ount SM 16 I NEMA 2 NEMA <sup>-</sup> BE 23 II Optior None	In-Line 23 In-Li 17 In-Li n-Line I	Mountii ne Mou ne Mou Mountir	ng Inting Inting		
	H9 H11 H12 H13 H14	N.O. Current Sourcing N.C. Current Sinking S N.O. Current Sinking S N.C. Current Sourcing N.O. Current Sourcing	Sensor Pack Sensor Pack Sensor Pac	k		10	E2 E3 E4 R1		1.0 μm 0.5 μm 0.1 μm Require	Resolu Resolu	tion tion			

#### \* Drive Screw Lead Availability

Travel	40	2XR
Iravei	5 mm	10 mm
100	•	
150	•	
200	•	
300		•
400		•
600		•



			1	2	3	4	5	6	7	8	9	10	11	12	(13)	14
	Order	Example:	404	450	XR	М	S	- D33	H4	L2	C3	M4	E1	B1	R1	P1
0	Series								H8	N.C	. Curre	nt Sour	cing Loo	cking C	onnecto	or*
•	404								H9				cing Loo	-		
									H11				ng Sens	-		
2	Travel -	- mm *							H12				ng Sens			
	050	50 (no pinnin	g availabl	le)					H13	N.C	. Curre	nt Sour	cing Ser	nsor Pa	ck**	
	100	100							H14	N.O	. Curre	nt Sour	cing Sei	nsor Pa	ck**	
	150 200	150 200														
	200 250	250						8	Trave	Limit	Senso	r Asse	mbly (t	two se	nsors)	
	300	300							L1	Non	e-Free	Travel (	only)			
	350	350							L2	N.C	. Curre	nt Sinkir	ng Flying	g Leads	6	
	400	400							L3	N.O	. Curre	nt Sinkiı	ng Flyin	g Leads	6	
	450	450							L4	N.C	. Curre	nt Sour	cing Flyi	ing Lead	ds	
	500	500							L5	N.O	. Curre	nt Sour	cing Flyi	ing Lea	ds	
	550	550							L6	N.C	. Curre	nt Sinkir	ng w/Lc	ocking C	Connect	or*
	600	600							L7	N.O	. Curre	nt Sinkii	ng w/Lo	ocking (	Connect	tor*
ୢ	Model								L8	N.C	. Curre	nt Sour	cing w/L	_ocking	Conne	ctor*
3	XR	Linear Table							L9				cing w/l	-		ctor*
	лп	Linear Table							L11				ng Sens			
4	Mounti	20							L12				ng Sens			
G	M	Metric							L13				cing Ser			
	141	Metho							L14	N.O	. Curre	nt Sour	cing Sei	nsor Pa	.ck**	
5	Grade							0	Motor	Coupl	ing					
	S	Standard							C1	No (	Couplin	g (requi	ired for	parallel	mounti	ng)
	Р	Precision (only screws)	available	with D2	2, D3, L	J4 arive			C2	0.25	50" Old	ham				
		3010103/							C3	0.25	50" Bell	ows (re	quired f	or preci	sion gra	ade)
6	Drive S	crew							C4	0.37	'5" Old	ham				
•	D1	Free Travel							C5	0.37	'5" Bell	ows (re	quired f	or preci	sion gra	ade)
	D2	5 mm Ballscre	W						C6	11 r	nm Old	ham				
	D3	10 mm Ballscr	ew						C7	11 r	nm Bel	lows (re	equired f	for prec	ision gr	ade)
	D4	20 mm Ballscr	ew (stand	dard gra	de only	/)			C10	14 r	nm Old	lham (N	175 mot	or optic	on)	
	D31	1 mm V Threa	d Leadsc	rew					C11	14 r	nm Bel	lows (M	175 mot	or optic	n)	
	D32	2 mm V Threa	d Leadsc	rew					C22	9 m	m Oldh	am				
	D33	5 mm V Threa	d Leadsc	rew					C23		m Bello					
	D34	0.10" V Thread	d Leadsci	rew					C24	5 m	m Oldh	am (M3	87 moto	r optior	1)	
	D35	0.10" Acme Th	hread Lea	adscrew	,				C25				87 moto			
									C26	8 m	m Oldh	am (M7	'1 moto	r optior	1)	
0	Home S	Sensor Assem		senso	r)				C27				'1 moto			
	H1	None-Free Tra							C28			,	<b>1</b> 37 mo		,	
	H2	N.C. Current S	• •						C29				И37 mo			
	H3	N.O. Current S		-					C30				ouplings 			
	H4	N.C. Current S	-						C31				ouplings			
	H5	N.O. Current S	-						C32				ouplings 			
	H6	N.C. Current S	-						C33				ouplings			
	H7	N.O. Current S	Sinking Lo	ocking C	Connect	tor*			C39	9 m	m Bello	ws (cou	uplings	tor lead	screw g	grade)

\* Sensors with locking connector include 5 m extension cable. \*\* Sensor Pack includes 3 m cable.

## **404XR Ordering Information**



#### ator Mount \* 10

Motor N	lount *
M1	No Motor Mount
M2	SM 16 In-Line Mounting
M3	NEMA 23 & SM 23 In-Line Mounting
M4	NEMA 34 In-Line Mounting
M5	SM 16 Parallel Mounting, "A" Location*
M6	SM 16 Parallel Mounting, "B" Location*
M7	SM 16 Parallel Mounting, "C" Location*
M8	NEMA 23 Parallel Mounting, "A" Location*
M9	NEMA 23 Parallel Mounting, "B" Location*
M10	NEMA 23 Parallel Mounting, "C" Location*
M11	SM 23 Parallel Mounting, "A" Location*
M12	SM 23 Parallel Mounting, "B" Location*
M13	SM 23 Parallel Mounting, "C" Location*
M21	Neometric 70 In-Line Mounting
M37	NEMA 17 In-Line Mounting
M42	SM232AQ NPSN Servo Motor In-Line Mounting
M46	HV232-02-10 Stepper Motor In-Line Mounting
M49	Handcrank without Readout
M50	Handcrank with Readout (0.10" or 1 mm leads only)
M61	BE 23 In-Line Mounting
M62	BE 23 Parallel Mounting, "A" Location*
M63	BE 23 Parallel Mounting, "B" Location*
M64	BE 23 Parallel Mounting, "C" Location*
M71	SCM01 In Line Mounting

- M71 SGM01 In-Line Mounting
- M75 SGM02 In-Line Mounting

\* See 404XR dimensions for maximum allowable motor shaft diameter. Parallel motor mounts not available with leadscrew drives.

#### (1)**Encoder Option**

- E1 No Encoder
- E2 1.0 µm Resolution Linear Encoder (tape scale)
- E3 0.5 µm Resolution Linear Encoder (tape scale)
- E4 0.1 µm Resolution Linear Encoder (tape scale)
- E5 Rotary Shaft Encoder (not available with brake)

#### (12) **Brake Option**

- B1 No Brake
- **B**2 Shaft Brake (Refer to 404XR holding torque specifications to confirm maximum load. Not available with rotary encoder)

#### (13) **Cleanroom Preparation**

- R1 Class 1000 Compatible
- **R2** Class 10 Compatible (consult factory)
- R5 Class 1000 with Easy Lube System
- R8 Class 10 with Easy Lube System

#### (14) **Pinning Option \***

- **P1** No multi-axis pinning P2 X axis transfer pinning to Y or Z axis - 30 arc-sec \*\* P3 Y axis transfer pinning to X axis - 30 arc-sec Ρ4 Z axis transfer pinning to X axis - 30 arc-sec P5
  - X axis transfer pinning to Y axis 125 arc-sec
  - **P6** Y axis transfer pinning to X axis - 125 arc-sec \* Pinning option is for pinning to other 404XR and 406XR tables. Transfer pinning is not available on some XR to LXR models.

Contact factory for more information. Pinning XY orientation standard with Y motor at 3 o'clock position. \*\* Z pinning uses bracket (see figures 7, 8 and 9 on page 47)



			1	2	3	4	5	6	7	8	9	10	11	12	(13)	[14	
	Order I	Example:	406	900	XR	М	S -	- D3	H4	L1	C7	M4	E1	B1	R1	P	
1	<mark>Series</mark> 406							8	L1	el Limit Nor	ne				sors)		
0	Travel – 100 200 300 400 500 600 700 800 900 1000 1250 1500 1750 2000	mm * 100 200 300 400 500 600 700 800 900 1000 1250 1500 1750 2000						•	L2 L3 L4 L5 L6 L7 L8 L9 L11 L12 L13 L14	N.C N.C N.C N.C N.C N.C N.C N.C N.C N.C	C. Currer C. Currer C. Currer C. Currer C. Currer C. Currer C. Currer C. Currer C. Currer C. Currer	nt Sinkirn nt Sourc nt Sourc nt Sinkirn nt Sinkirn nt Sourc nt Sinkirn nt Sinkirn nt Sourc nt Sourc	ng Flying Flying Flyir ing Flyir ing w/Loo ing w/Loo ing w/Loo ing w/Loo ing w/Loo ing w/Loo ing Senso ing Senso ing Senso ing Sen	Leads ng Leads ng Leads cking Co cking Co cocking ( ocking ( or Pack or Pack sor Pac sor Pac	s onnect onnect Connec Connec Connec *** ** ** K	ctor** ctor* ctor*	
3	Model	2000							C1 C2		Couplin 50" Oldł		red for p	arallel n	nountir	ng)	
9	XR	Linear Table							C3 C4	0.3	50" Belle 75" Oldł	nam			-		
4	<mark>Mounti</mark> n M	<b>9</b> Metric							C5 C6 C7	11	75" Bello mm Old mm Bell		-				
5	Grade *								C8 C9	<ul><li>11 mm Bellows (required for precision g</li><li>0.500" Oldham</li><li>0.500" Bellows (required for precision g</li></ul>							
	S P	Standard Precision							C10 C11	14	mm Old mm Bell	ham			-		
6	Drive Sc	rew *							C12 C13		mm Old mm Bell		a uirod f		ion ar	ada)	
	D1 D2 D3	Free Travel 5 mm Ballscrew 10 mm Ballscre						*	Drive S			·			ion gro	400)	
	D4 D5	20 mm Ballscre 25 mm Ballscre						ſ	Travel	Prec Gra	ision ade		Standa		-		
$\sim$								ŀ	100	<u>5 mm</u>	10 mm •	<u>5 mm</u>	10 mm	20 mm	25 m	m	
0	Home S H1	ensor Assemb None	iy (one	senso	r)			F	200 400	•	•	•	•	•		$\square$	
	H2	N.C. Current Sir	okina Elv	vina Lea	de			F	400	•	•	•	•	•			
	H3	N.O. Current Sir		-				F	500	•	•	•	•	•			
	H4	N.C. Current Sc				F	<u>600</u> 700	•	•	•	•	•	•				
	H5	N.O. Current Sc				Ľ	800			•	•		•				
	H6	N.C. Current Sir	•			0r**		-	<u>900</u> 1000			•	•		•		
	H7	N.O. Current Sir	0	0				F	1250			•	•		•		
	H8	N.C. Current Sc	-	-				F	1500			•	•		•		
	H9	N.O. Current Sc N.O. Current Sc	-	-				┝	1750 2000			•	•		•	$\neg$	
	H11	N.C. Current Sir	-	-		5.01		L	2000	1	1	1	1	1	1		
	****		-					** 60	nooro witi	h looking	connocto	or include	5 m ovt	onoion or	blo		
	H12	NO Current Qi	nkina Sa	nsor Dr	ack***										abie.		
	H12 H13	N.O. Current Sin N.C. Current Sc	-						ensor Pac				5 J III GAL		idie.		







#### M1 No Motor Mount М3 NEMA 23 & SM 23 In-Line Mounting M4 NEMA 34 In-Line Mounting M11 SM 23 Parallel Mounting, "A" Location\* M12 SM 23 Parallel Mounting, "B" Location\*

Motor Mount \*

(10)

- M13 SM 23 Parallel Mounting, "C" Location\*
- M14 NEMA 34 Parallel Mounting, "A" Location
- M15 NEMA 34 Parallel Mounting, "B" Location
- M16 NEMA 34 Parallel Mounting, "C" Location
- M17 Neometric 34 In-Line Mounting
- M18 Neometric 34 Parallel Mounting, "A" Location
- M19 Neometric 34 Parallel Mounting, "B" Location
- M20 Neometric 34 Parallel Mounting, "C" Location
- M21 Neometric 70 In-Line Mounting
- M22 Neometric 70 Parallel Mounting, "A" Location
- M23 Neometric 70 Parallel Mounting, "B" Location
- M25 Neometric 70 Parallel Mounting, "C" Location
- M29 Neometric 92 In-Line Mounting
- M61 BE 23 In-Line Mounting
- M62 BE 23 Parallel Mounting, "A" Location
- M63 BE 23 Parallel Mounting, "B" Location
- M64 BE 23 Parallel Mounting, "C" Location
- M75 SGM02 In-Line Mounting
- M90 MPP092 In-Line Mounting
- M91 MPP092 Parallel Mounting, "A" Location
- M92 MPP092 Parallel Mounting, "B" Location
- M93 MPP092 Parallel Mounting, "C" Location

\* See 406XR dimensions for maximum allowable motor shaft diameter. SM 23 parallel motor mounts not available with leadscrew drives.

#### **Encoder Option** (1)

- E1 No Encoder
- F2 1.0 µm Resolution Linear Encoder (tape scale)
- E3 0.5 µm Resolution Linear Encoder (tape scale)
- E4 0.1 µm Resolution Linear Encoder (tape scale)
- E5 Rotary Shaft Encoder (not available with brake)

#### (12) **Brake Option**

- B1 No Brake
- B2 Shaft Brake (Refer to 406XR holding torque specifications to confirm maximum load. Not available with rotary encoder)

#### (13) **Cleanroom Preparation**

- **R1** Class 1000 Compatible
- R2 Class 10 Compatible (consult factory)
- **R**5 Class 1000 with Easy Lube System
- R8 Class 10 with Easy Lube System

#### (14) **Pinning Option \***

- **P1** No multi-axis pinning
- **P2** X axis transfer pinning to Y or Z axis - 30 arc-sec \*\*
- **P**3 Y axis transfer pinning to X axis - 30 arc-sec
- **P**4 Z axis transfer pinning to X axis - 30 arc-sec

\* Pinning option is for pinning to other 404XR and 406XR tables. Transfer pinning is not available on some XR to LXR models. Contact factory for more information. Pinning XY orientation standard with Y motor at 3 o'clock position. \*\* Z pinning uses bracket (see figures 7, 8 and 9 on page 47)

Parker Hannifin Corporation Electromechanical Automation Division Irwin, Pennsylvania



			1	2	3	4	5	6	0	8	9	10	11	12	13	14
	<b>•</b> • •														-	
	Order	Example:	412	T03	XR	М	s -	D2	H3	L3	C15	M4	E3	B1	R1	P1
1	Series							8	Travel	Limit	Senso	r*				
-	412								L1	Nor	ne					
~									L2	N.C	C. Currer	nt Sinkir	ng Flying	g Leads	3	
2	Travel –								L3	N.C	). Currei	nt Sinkir	ng Flyin	g Leads	3	
	T01 T02	150 250							L4	N.C	C. Currer	nt Sourc	cing Flyi	ing Lea	ds	
	T02 T03	350							L5		). Currei		• •	•		
	T04	650									neter exte sion cabl					ation. A
	T05	800							7.5 met		SIGN Cabi	e can be	Oldelec	i sepaia	leiy.	
	T06	1000						9	Motor	Coup	lina					
	T07	1200						0	C1		Couplin	a				
	T08	1500							C4		75" Oldi	•				
	Т09 Т10	1750 2000							C5		75" Bell					
	110	2000							C6	11	mm Old	ham				
3	Model								C7	11	mm Bell	lows				
0	XR	Linear Table							C8	0.5	00" Oldi	ham				
									C9	0.5	00" Bell	ows				
4	Mountir	na							C10	14	mm Old	ham				
•	М	Metric							C11	14	mm Bel	lows				
									C12	16	mm Old	ham				
5	Grade								C13	16	mm Bel	lows				
-	S	Standard							C14	0.7	50" (19	mm) Ol	dham			
									C15	0.7	50" (19	mm) Be	ellows			
6	Drive Se	crew														
	D1	Free Travel														
	D2	5 mm Leadscrev														
	D3	10 mm Leadscre														
	D5	25 mm Leadscre														
	D6	32 mm Leadscre	ЭW													
0	Home S	ensor *														
0	H1	None														

- H2 N.C. Current Sinking Flying Leads
- H3 N.O. Current Sinking Flying Leads

H4 N.C. Current Sourcing Flying Leads

H5 N.O. Current Sourcing Flying Leads

\* Includes a 3 meter extension cable with flying lead termination. A 7.5 meter extension cable can be ordered separately.







#### (1) Motor Mount

M1	No Motor Mount
M4	NEMA 34 In-Line Mounting
M14	NEMA 34 Parallel Mounting, "A" Location
M15	NEMA 34 Parallel Mounting, "B" Location
M17	Neometric 34 In-Line Mounting
M18	Neometric 34 Parallel Mounting, "A" Location
M19	Neometric 34 Parallel Mounting, "B" Location
M21	Neometric 70 In-Line Mounting
M22	Neometric 70 Parallel Mounting, "A" Location
M23	Neometric 70 Parallel Mounting, "B" Location
M29	Neometric 92 In-Line Mounting
M30	Neometric 92 Parallel Mounting, "A" Location
M31	Neometric 92 Parallel Mounting, "B" Location
M33	M105 & SMN100 In-Line Mounting
M90	MPP092 In-Line Mounting
M91	MPP092 Parallel Mounting, "A" Location
M92	MPP092 Parallel Mounting, "B" Location

M93 MPP092 Parallel Mounting, "C" Location

#### **Encoder Option**

- E1 No Encoder
- E2 1.0 µm Resolution Linear Encoder (tape scale)
- E3 0.5 µm Resolution Linear Encoder (tape scale)
- E4 0.1 µm Resolution Linear Encoder (tape scale)
- **E5** 5.0 μm Resolution Linear Encoder (tape scale)
- E6 Rotary Shaft Encoder (not available with brake)
- E7 Sine Encoder

#### Brake Option

- B1 No Brake
- B2 Shaft Brake (Refer to 412XR holding torque specifications to confirm maximum load. Not available with rotary encoder)

#### **13** Cleanroom Preparation

- R1 Class 1000 with Strip Seals
- R2 Class 100 without Strip Seals

#### ( Pinning Option \*

- P1 No multi-axis pinning
- P2 X axis transfer pinning to Y or Z axis 30 arc-sec \*\*
- P3 Y axis transfer pinning to X axis 30 arc-sec (includes a required 15 mm thick adapter)
- P4 Z axis transfer pinning to X axis 30 arc-sec

\* Pinning option is for pinning to other 404XR and 406XR tables. Transfer pinning is not available on some XR to LXR models. Contact factory for more information. Pinning XY orientation standard with Y motor at 3 o'clock position.

\*\* Z pinning uses bracket (see figures 7, 8 and 9 on page 47)

